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Langley Research Center



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Wide Deviation Phase Modulator

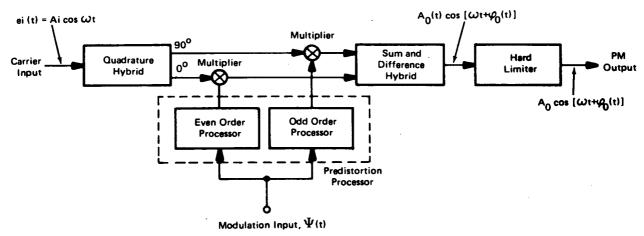


Figure 1. Functional Diagram of Phase Modulator

A modulator was designed to produce a phase-modulated (PM) waveform having high modulating linearity. Practical circuits utilizing the technique described have been constructed and evaluated for peak phase deviations as large as 5 radians. Additionally, the technique is inherently wideband with respect to carrier frequency and can operate over a decade carrier frequency range without adjustments. Circuit performance is both mathematically predictable and highly reproducible.

Mathematically, an ideal PM waveform may be expressed as

$$e(t) = R\dot{e}\left\{Ae^{j\left[\omega t + \Psi(t)\right]}\right\}$$
 (1)

where A is the carrier amplitude, ω is the carrier radian frequency, and $\Psi(t)$ is the modulating function. Equation 1 can be rewritten as either

e(t) =
$$[A \cos \omega t \cos \Psi(t)] - [A \sin \omega t \sin \Psi(t)]$$
 (2)

or
$$e(t) = A \left[1 - \frac{\Psi^{2}(t)}{2!} + \frac{\Psi^{4}(t)}{4!} - \dots \right] \cos \omega t$$

$$-A \left[\Psi(t) - \frac{\Psi^{3}(t)}{3!} + \frac{\Psi^{5}(t)}{5!} - \dots \right] \sin \omega t \quad (3)$$

The configuration shown in Figure 1 performs the operations indicated in equations 2 and 3. Sine and cosine modules are commercially available; however, they are at present two-quadrant ($\pm 90^{\circ}$) devices. This technique uses truncated power series processors and determines the coefficients for producing the best modulating linearity. The modulated phase of e(t), $\varphi_0(\Psi)$, is

$$\varphi_0(\Psi) = \tan^{-1} \left[\frac{\Psi - k_3 \Psi^3 + k_5 \Psi^5 - \dots}{1 - k_2 \Psi^2 + k_4 \Psi^4 - \dots} \right]$$
 (4)

(continued overleaf)

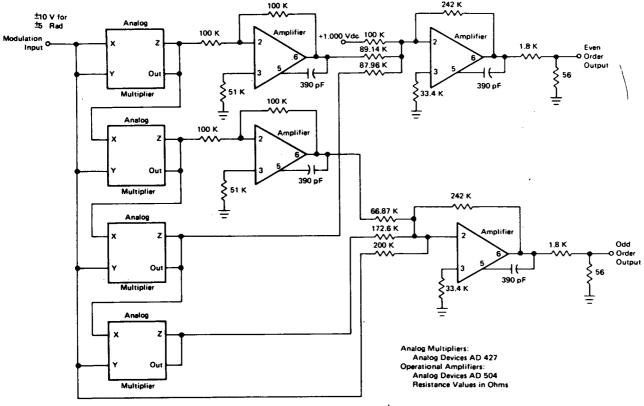


Figure 2. Fifth Order Processor for ±5 Radians

where the k_i are the coefficients of the nonlinear processors and should be chosen to make $\varphi_0(\Psi)$ a best approximation to Ψ . Optimization can be based on various criteria. Two commonly used criteria are minimum mean square error (MMSE) between $\varphi_0(\Psi)$ and Ψ and minimum total harmonic distortion (MTHD) for Ψ a sinusoidal signal. Computer programs have been developed to minimize the integral expressions defining MSE and THD for an arbitrary number of independent variables.

Figure 2 is the diagram of a fifth order MMSE predistortion processor designed for ±5 radians. The optimum coefficients are: $k_2 = 0.448754$, $k_3 = 0.119633$, $k_4 = 0.0181933$, and $k_5 = 0.00185463$. Considerable care should be used in component selection and application. Resistors were trimmed to 0.1 percent, and the balanced mixers were slope matched to about 1 percent. Residual amplitude modulation (AM) on the order of 12 dB was fully suppressed with a limiter which exhibited negligible AM-to-PM conversion. Whereas theory predicts the fifth order MMSE realization should show a maximum deviation of 1° from the best straight line, the measured data for a practical circuit showed a 4.6° deviation or 1.6 percent of full scale. The upper modulation frequency response for this circuit was limited to about 25 kHz by the operational amplifiers.

Note:

No further documentation is available. Specific questions, however, may be directed to:

Technology Utilization Officer Langley Research Center Mail Stop 139-A Hampton, Virginia 23665 Reference: B74-10178

Patent status:

Inquiries concerning rights for the commercial use of this invention should be addressed to:

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